MEE5114 Spring 2023

Homework # 3

Due: March 19, 2023

Assigned March 12th, 2023

1. Modern Robotics: Exercise 3.20

2. Modern Robotics: Exercise 3.23

3. Modern Robotics: Exercise 3.26

4. Modern Robotics: Exercise 3.28

5. Modern Robotics: Exercise 5.5

6. Modern Robotics: Exercise 5.6 (Note: part-(a) is modified to compute the twist of frame {b} expressed in frame {b}, i.e., the ${}^{b}V_{b}$)